

Linear Equations
Gaussian Elimination and Matrices
Gauss–Jordan Method
Two-Point Boundary Value Problems
Making Gaussian Elimination Work
Ill-Conditioned Systems
Rectangular Systems and Echelon Form
Row Echelon Form and Rank
Reduced Row Echelon Form
Consistency of Linear Systems
Homogeneous Systems
Nonhomogeneous Systems
Electrical Circuits
Matrix Algebra
From Ancient China to Arthur Cayley
Addition and Transposition
Linearity
Why Do It This Way
Matrix Multiplication
Properties of Matrix Multiplication
Matrix Inversion
Inverses of Sums and Sensitivity
Elementary Matrices and Equivalence
The LU Factorization
Vector Spaces
Spaces and Subspaces
Four Fundamental Subspaces
Linear Independence
Basis and Dimension
Classical Least Squares
Linear Transformations
Change of Basis and Similarity
Invariant Subspaces